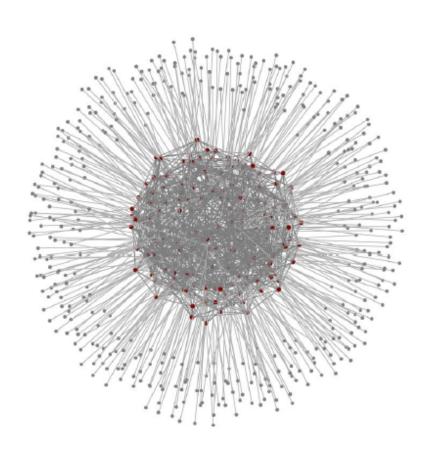
Jellyfish: Networking Data Centers Randomly

Ankit Singla, Chi-Yao Hong, Lucian Popa, Brighten Godfrey

Presented by Rashmi K. Vinayak 11/16/2015

(Many of the slides sourced from authors' presentations at NSDI '12 & DIMACS workshop '11)

How cool!





Jellyfish random graph

432 servers, 180 switches, degree 12

Jellyfish Arctapodema

Two goals

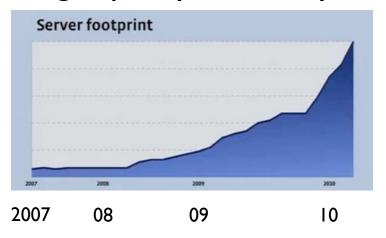
High throughput

Eliminate bottlenecks Agile placement of VMs Incremental expandability

Easily add/replace servers & switches

Incremental expansion

Facebook "adding capacity on a daily basis"

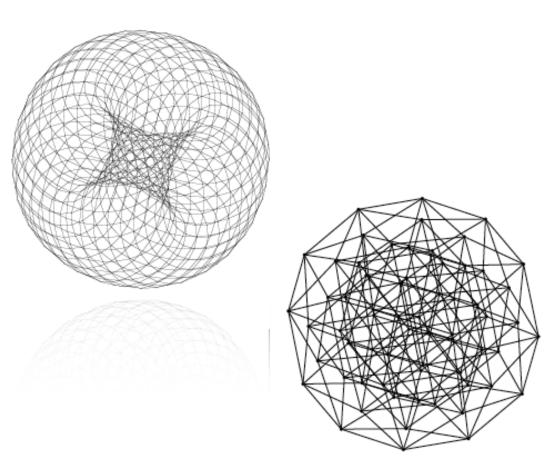


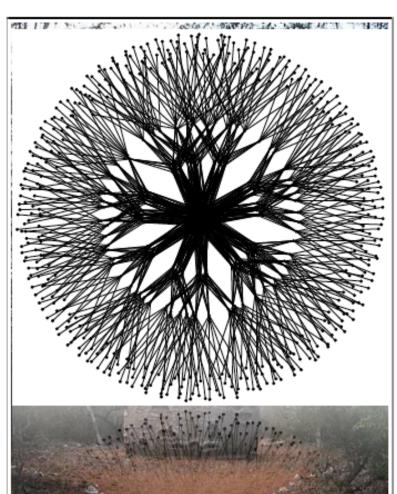
Commercial products

- SGI Ice Cube ("Expandable Modular Data Center")
- HP EcoPod ("Pay-as-you-grow")

You can add servers, but what about the network?

Today's structured networks





Structure constrains expansion

Coarse design points

- Hypercube: 2^k switches
- de Bruijn-like: 3^k switches
- 3-level fat tree: $5k^2/4$ switches

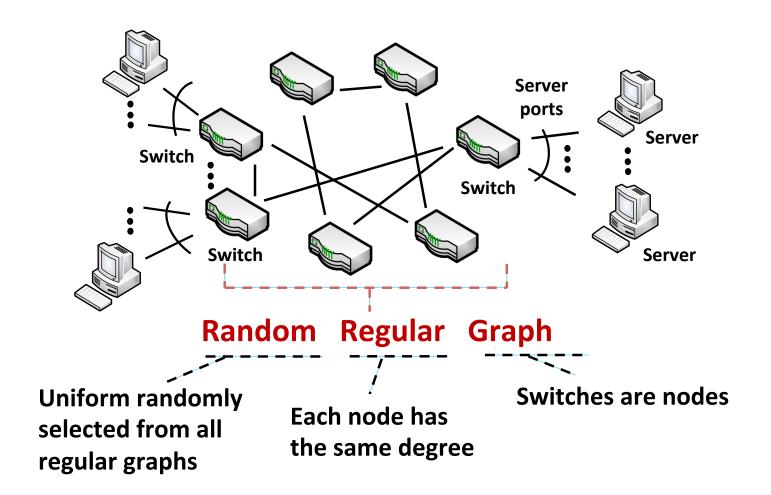
Fat trees by the numbers:

- (3-level, with commodity 24, 32, 48, ... port switches)
- 3456 servers, 8192 servers, 27648 servers, ...

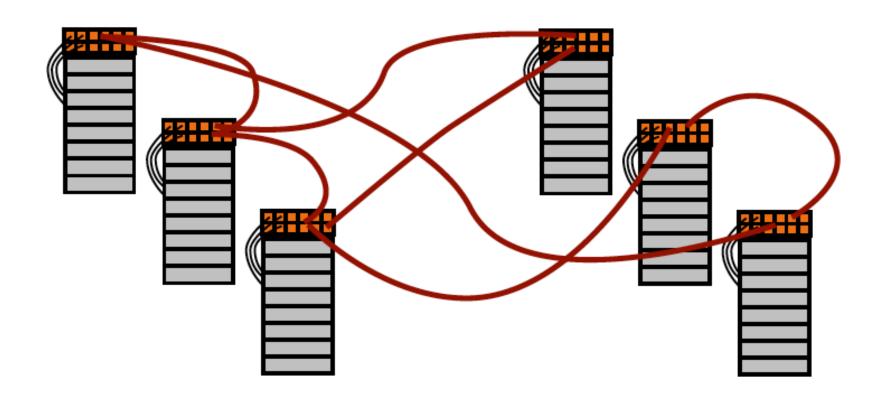
Unclear how to maintain structure incrementally

Forget about structure – let's have no structure at all!

Jellyfish: The Topology



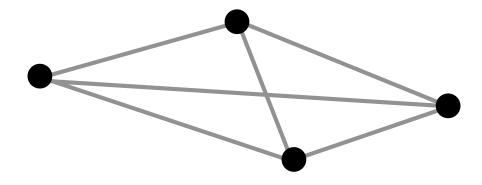
Jellyfish: The Topology



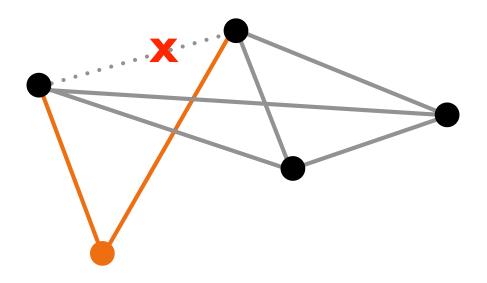
Servers connected to top-of-rack switch

Switches form uniform-random interconnections

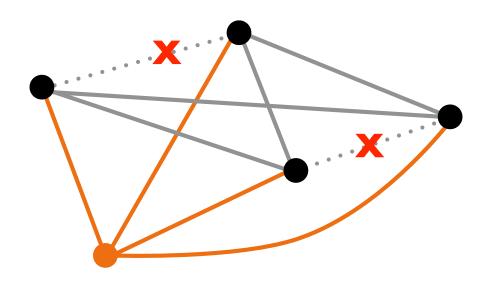
Building Jellyfish



Building Jellyfish



Building Jellyfish



Same procedure for initial construction and incremental expansion

Highly flexible

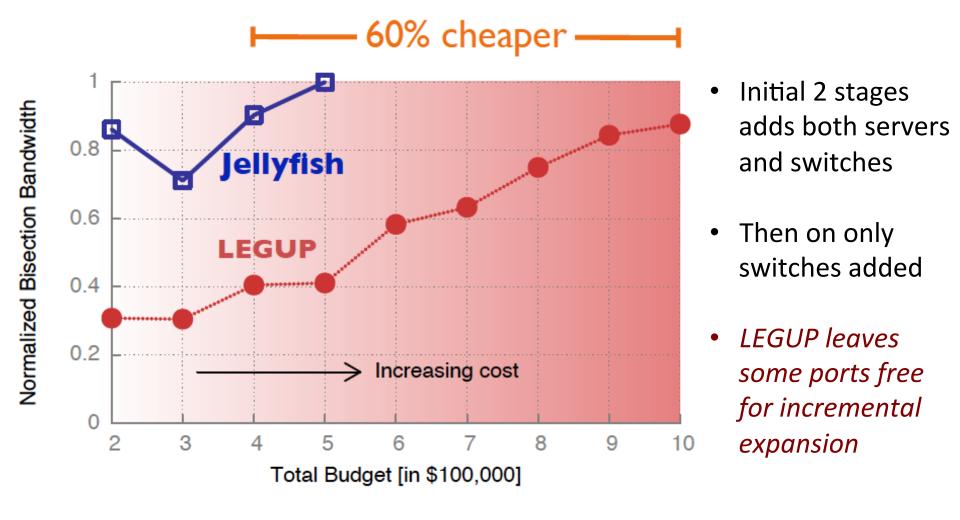
 few random swaps to incorporate additional components (both server racks and switches)

- supports heterogeneity naturally
 - newer network elements can have higher port counts

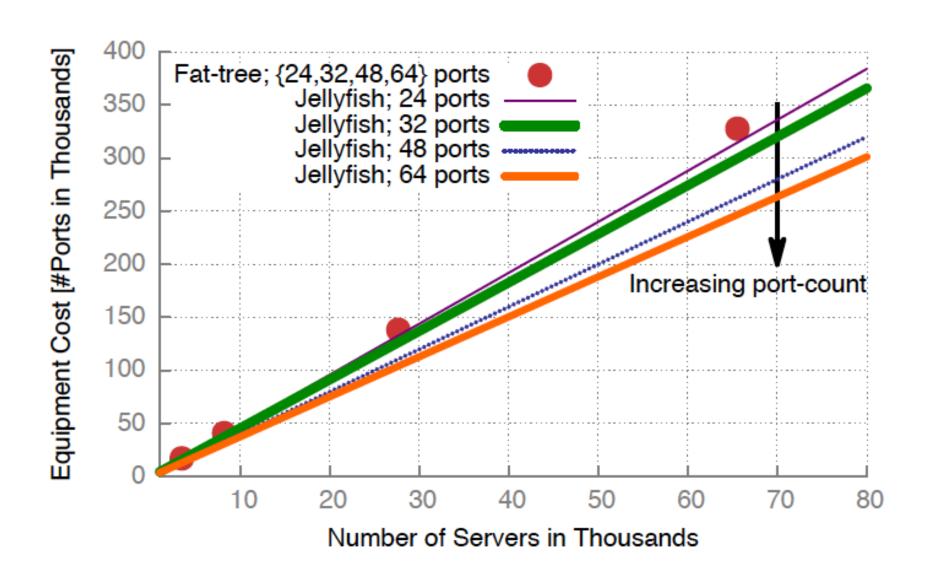
- allows construction of arbitrary sized networks
 - almost continuous design space
 - can add one rack or a switch at a time

Great for incremental expansion

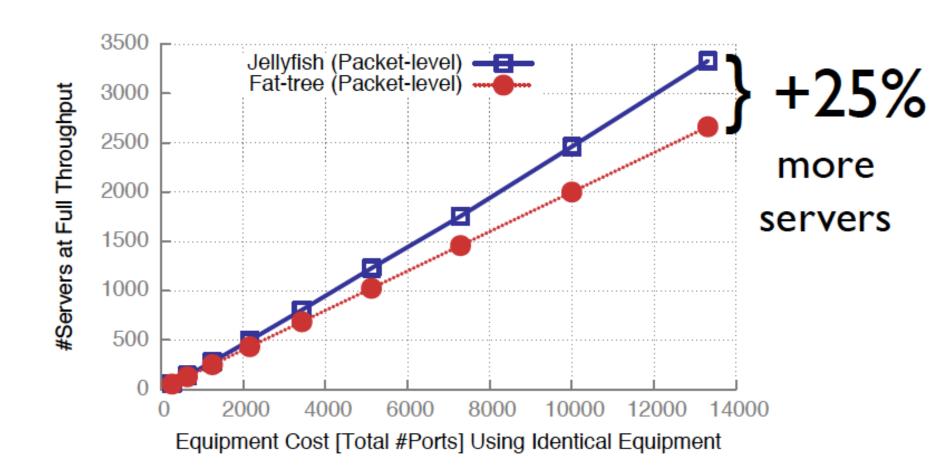
Quantifying expandability



Cost of building full bisection BW network



Throughput: Jellyfish vs. fat tree



Intuition

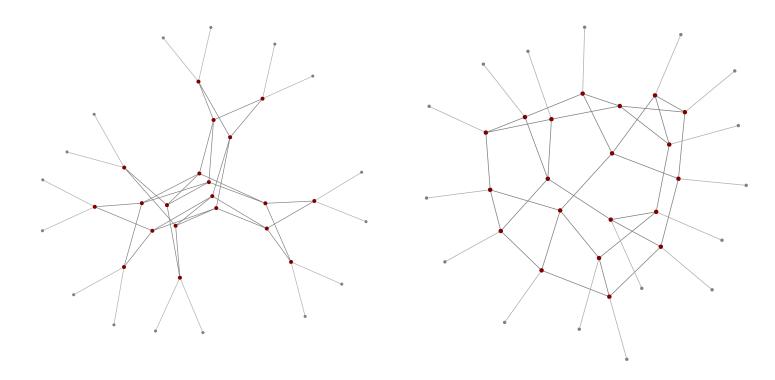
if we fully utilize all available capacity ...

I Gbps flows =
$$\frac{\sum_{links} capacity(link)}{l \text{ Gbps • mean path length}}$$

Mission: minimize average path length

minimize average path length

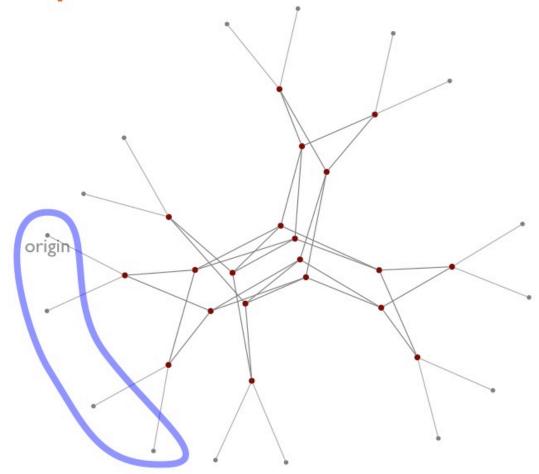
Example



Fat tree
16 servers, 20 switches, degree 4

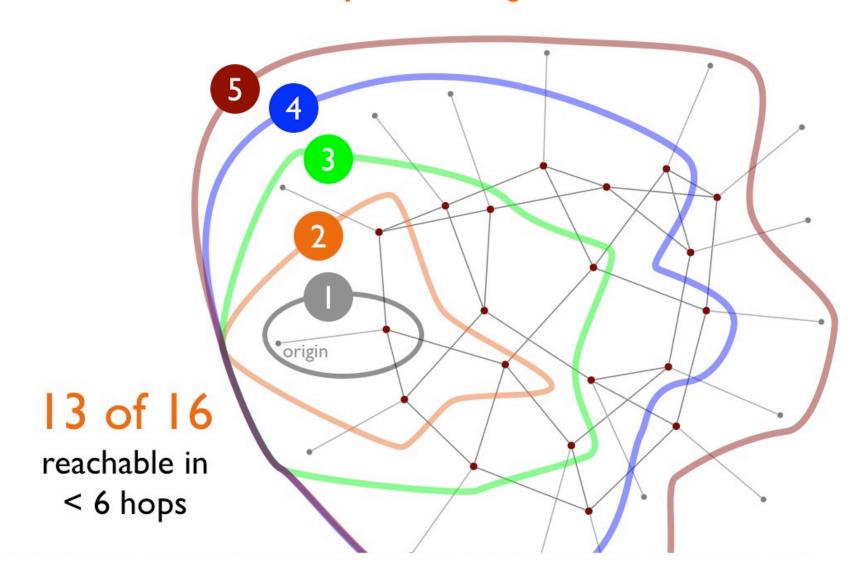
Jellyfish random graph
16 servers, 20 switches, degree 4

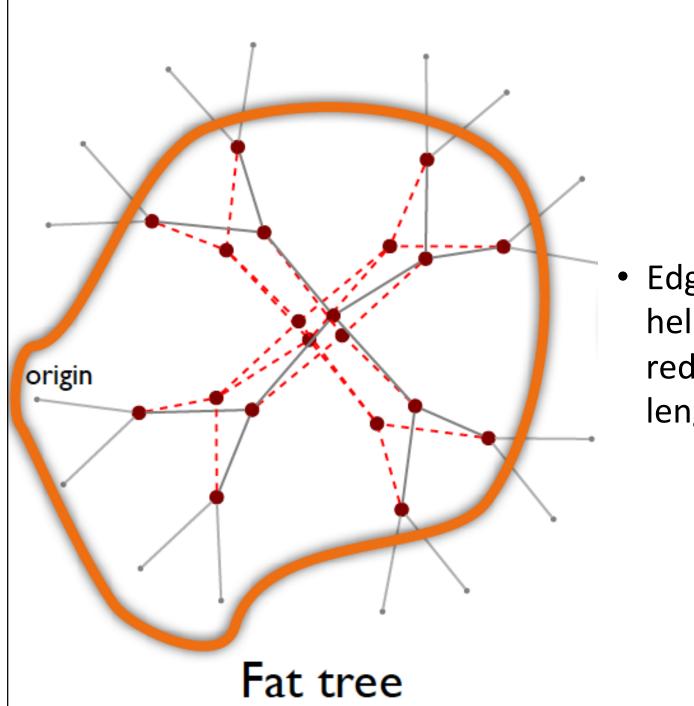
Example: Fat Tree



4 of 16 reachable in < 6 hops

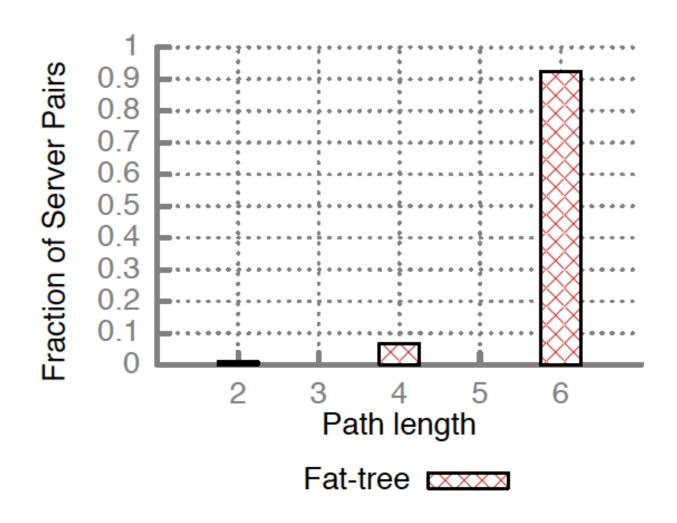
Example: Jellyfish





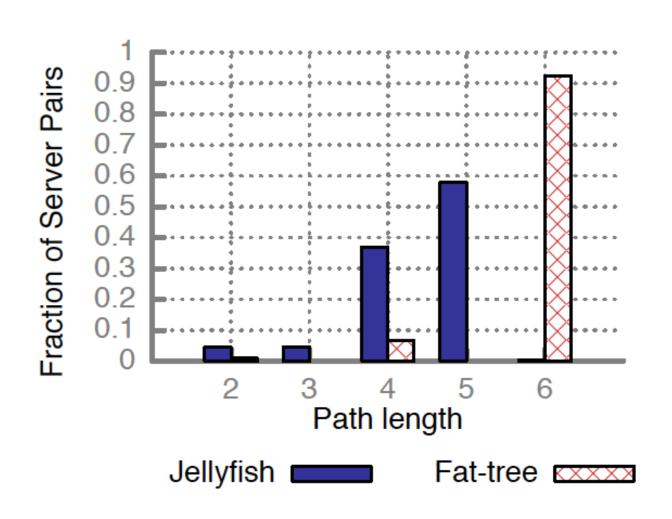
 Edges not helping in reducing path lengths

Jellyfish has short paths



Fat-tree with 686 servers

Jellyfish has short paths



Jellyfish, same equipment

Routing: a simple solution

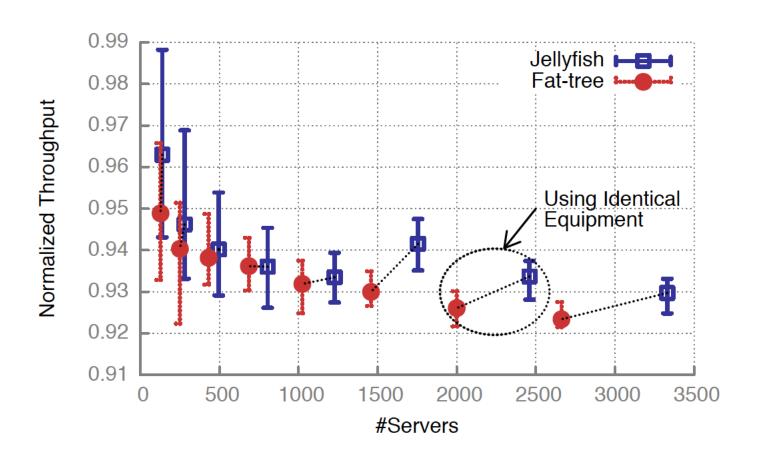
Find k shortest paths

Let Multipath TCP do the rest

[Wischik, Raiciu, Greenhalgh, Handley, NSDI'10]

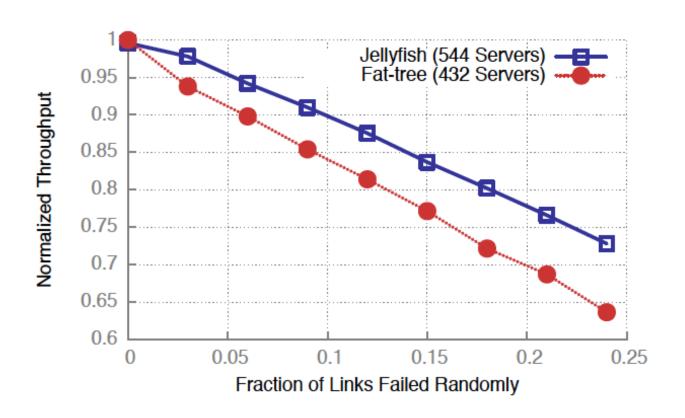


Fat-tree Throughput Comparison

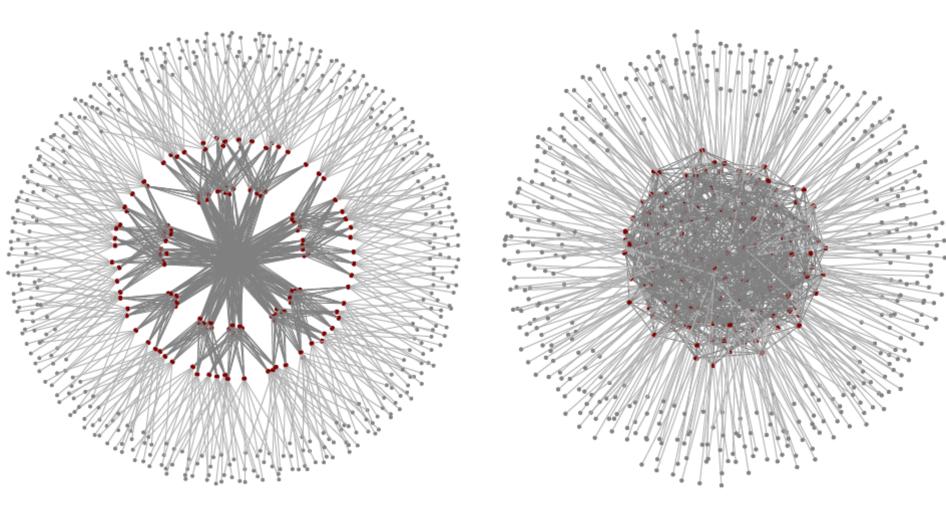


- Based on packet level simulations, including routing overheads
- Same hardware; more number of servers in Jellyfish than Fat-tree
- Similar stability

Throughput under link failures



Example



Fat tree 432 servers, 180 switches, degree 12

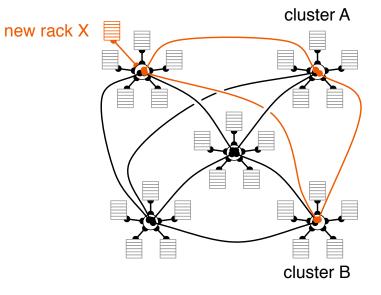
Jellyfish random graph 432 servers, 180 switches, degree 12

Cabling solutions

Fewer cables

for same # servers as fat tree

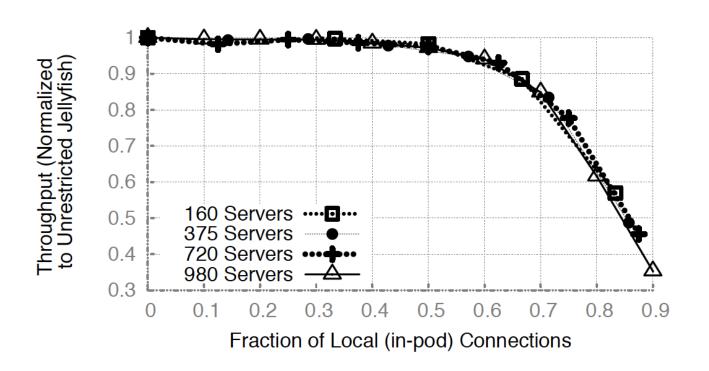
Aggregate bundles



Avoid long cables

< 5% loss of throughput

Cabling Jellyfish in Massive Scale DC



 <6% loss in throughput when 60% of the network connections per switch are localized

Discussion Points

- Real world impact what is the industry's take on this?
- Is the cabling issue for Jellyfish really resolved from the solutions offered?
 - Patch panels?
 - Is debugging a network of concern?

- Are the routing issues resolved?
 - k-shortest path routing?